Ceph: Software Defined Storage

UNIVERSITY OF OREGON

NSRC
Network Startup Resource Center

Why Ceph?

- Widely deployed and understood
  - Running at huge scale in many environments – e.g. DigitalOcean, CERN
- Many, many features
- Long history
  - Started in 2005 by Inktank
  - Red Hat purchased in 2014 (now IBM)
- Commercial distributions and support from multiple vendors

Features

- Block storage, File storage, Object storage
- Self healing, self balancing
- Very scalable
- Thin provisioning
- Cheap snapshotting and cloning
- Can be designed for high level of fault tolerance
- Off-site mirroring/replication natively supported

Downsides

- Steep learning curve
- Investment…
- Documentation is improving, but many advanced scenarios need some third party guidance
- Adding or removing nodes can cause a lot of data movement
  - Suggest starting with at least 5 nodes, so only ~20% of data moves
- Without proper operations and monitoring, it *can* fail

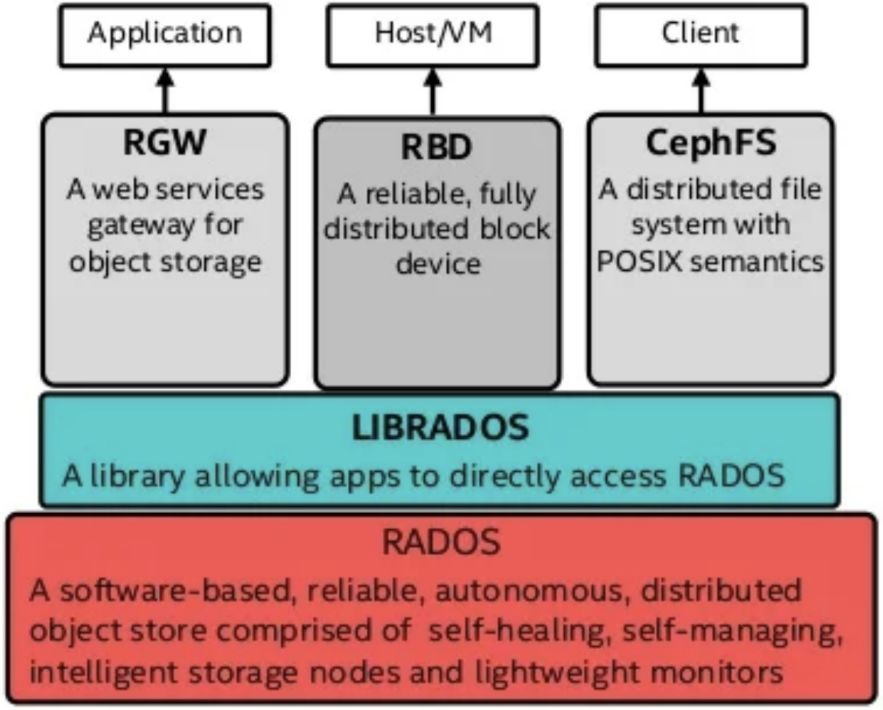
Main concepts

- RADOS - reliable autonomic distributed object store
- CRUSH map
- Placement groups - PGs
- MONs
- OSDs
- Pools

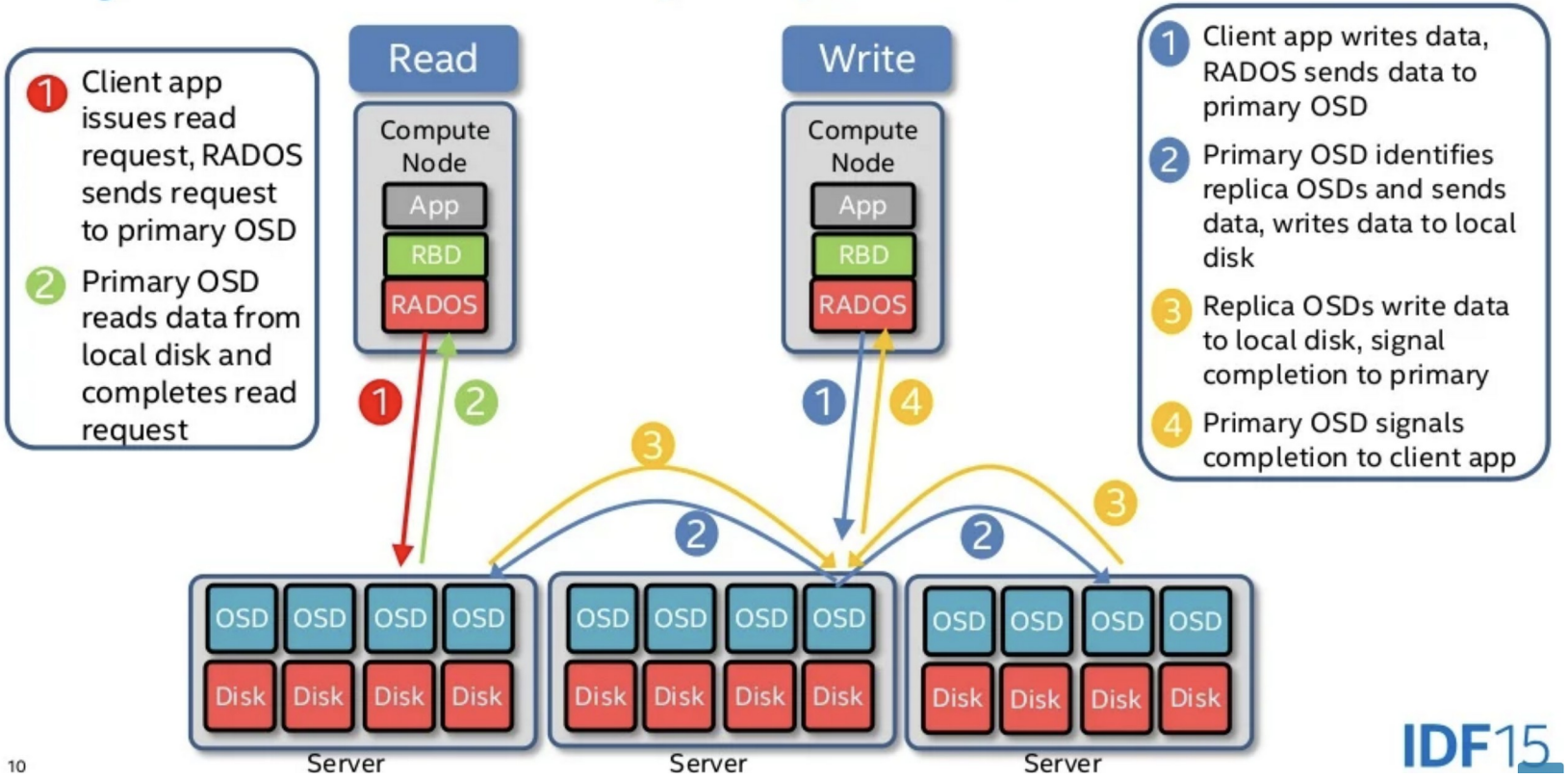
Components

- OSD daemon - stores data on one disk, on behalf of CEPH clients
- CEPH MONitor - maintains copy of the **cluster map**
- CEPH Manager (mgr) - info about PGs, metadata, collect stats
- Pools - logical partitions. Different pools for different types of data, replication policy, technology (SSD/HDD)
- Placement Group (pg) - a pool's data is spread across many PGs. PGs are then assigned to OSDs (by CRUSH)
- CRUSH is the algorithm and process for selecting data placement, failure domains, etc. based on rules.

Architecture

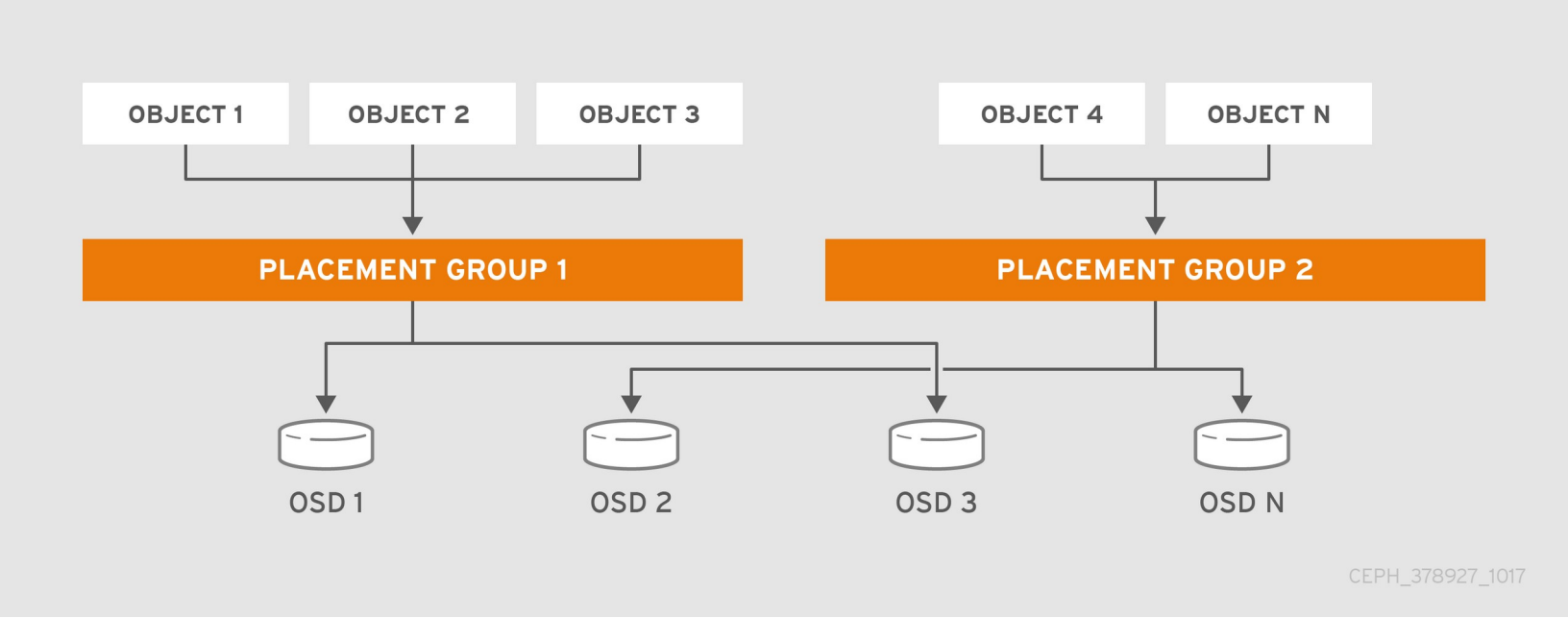


Object Store Daemon (OSD) Read and Write Flow

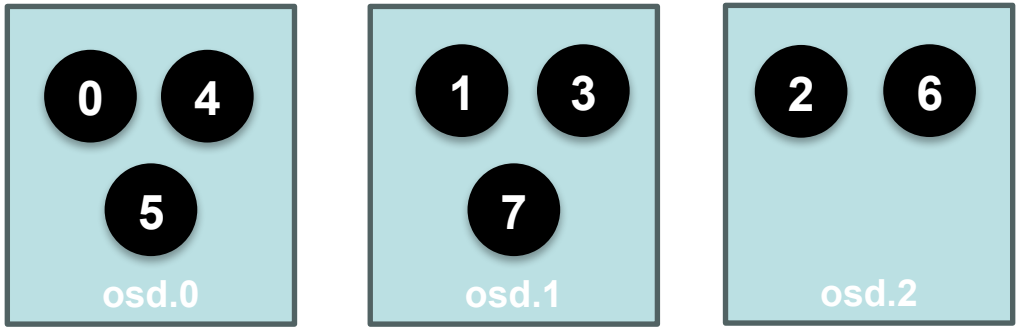


https://www.slideshare.net/LarryCover/ceph-open-source-storage-software-optimizations-on-intel-architecture-for-cloud-workloads

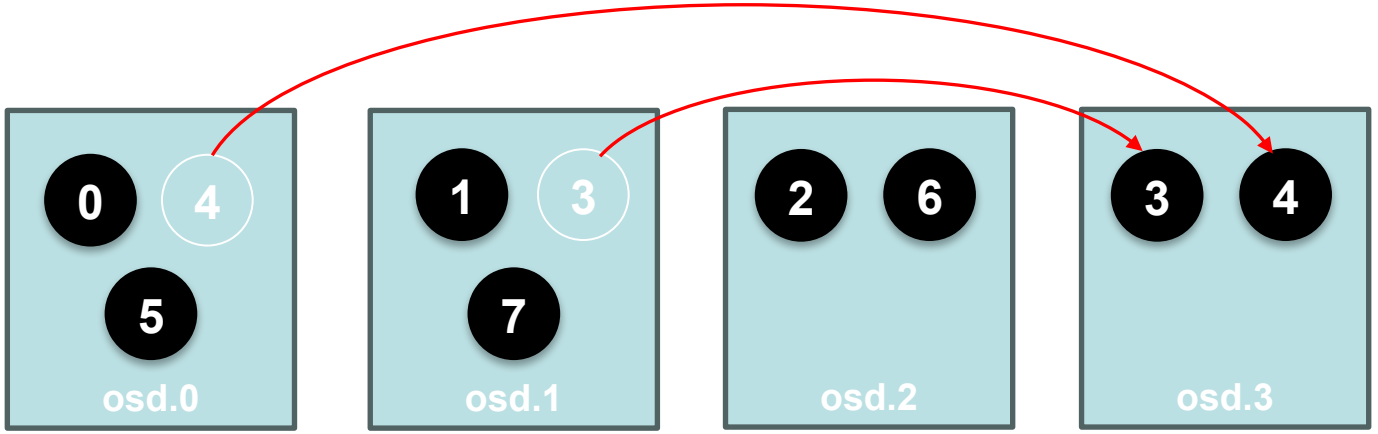
PGs, OSDs


OBJECT 1
OBJECT 2
OBJECT 3
OBJECT 4
OBJECT N
PLACEMENT GROUP 1
PLACEMENT GROUP 2
OSD 1
OSD 2
OSD 3
OSD N
CEPH_378927_1017

Assigning PGs to OSDs (cluster map)



Rebalancing - new OSD added



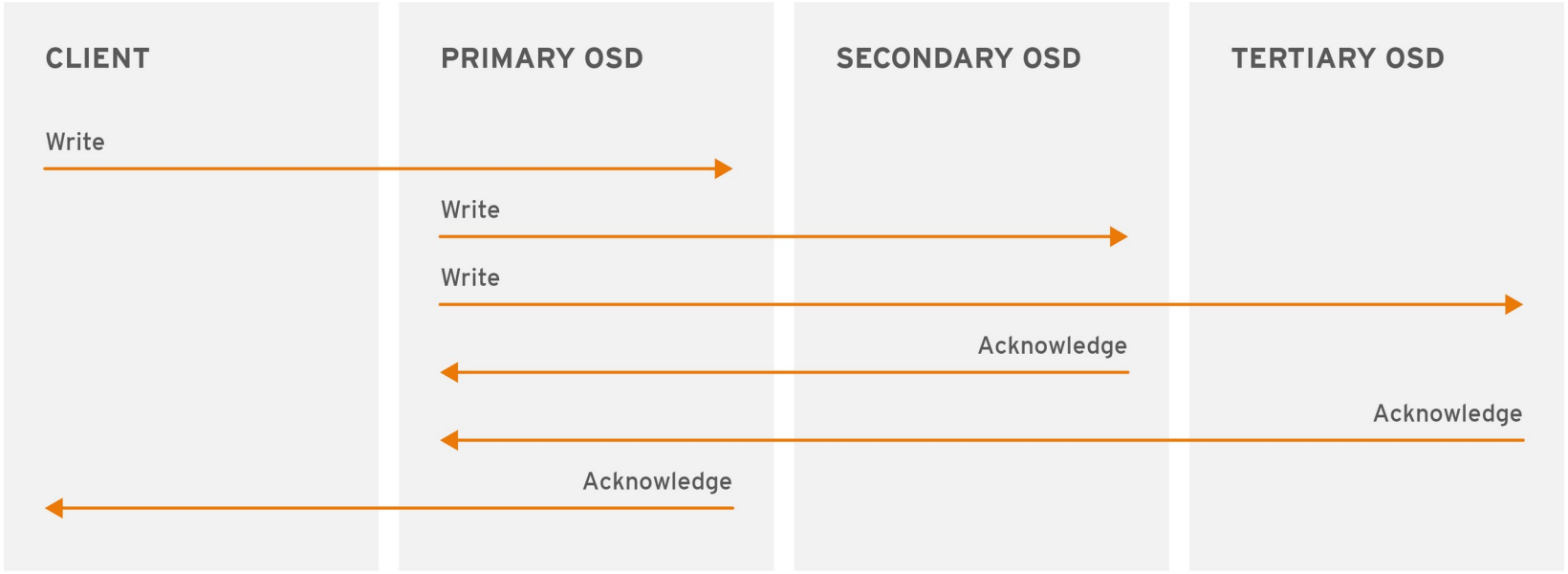
Algorithm moves minimum number of PGs

You need significantly *more* PGs in a pool than the number of OSDs in your cluster, to achieve good balance
(typical starting value: 128)

Where to place a new object?

- The client inputs the pool name and the object ID. For example, pool = liverpool and object-id = john.
  - CRUSH takes the object ID and hashes it.
  - CRUSH calculates the hash modulo of the number of PGs to get a PG ID. For example, 58.
  - CRUSH calculates the primary OSD corresponding to the PG ID.
  - The client gets the pool ID given the pool name. For example, the pool "liverpool" is pool number 4.
  - The client prepends the pool ID to the PG ID. For example, 4.58.
  - The client performs an object operation such as write, read, or delete by communicating directly with the Primary OSD in the Acting Set.

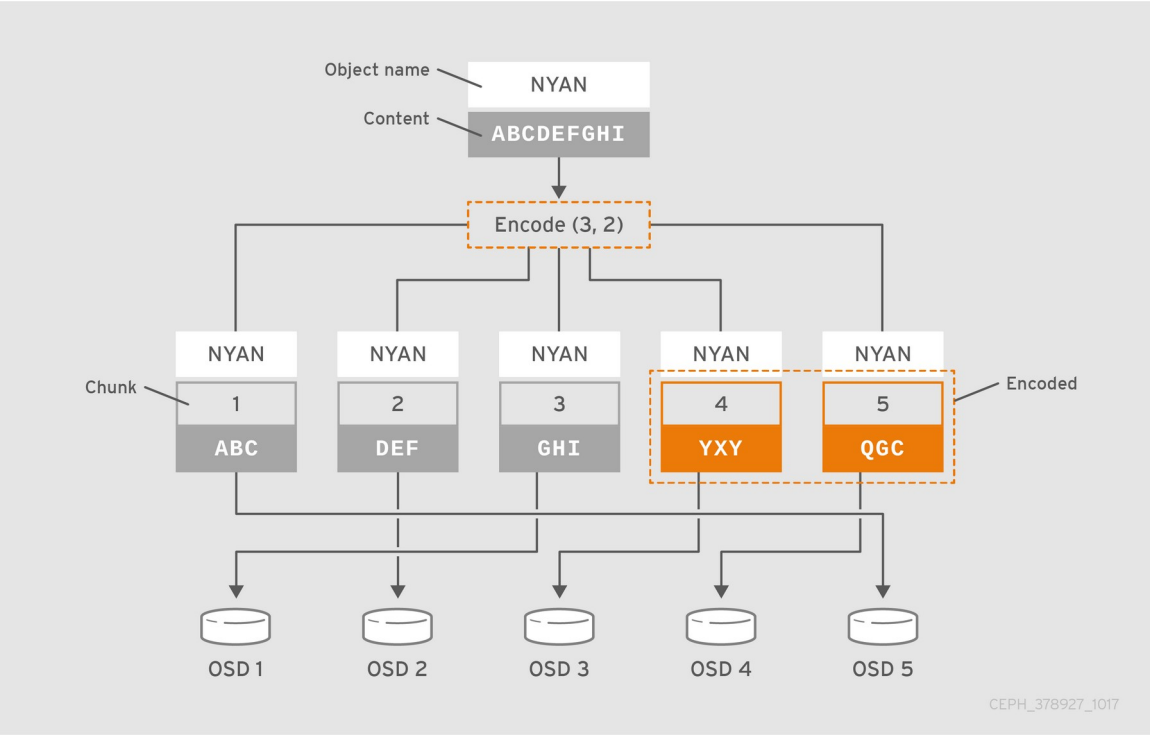
OSD replication



OSD states

- "Up" / "Down" = working / not working
- "In" / "Out" = enabled for use / not enabled for use
  - When a drive goes "Down", it's automatically made "Out"
  - You can manually set a drive to "Out", e.g. for maintenance
- Note that once a drive is Out, Ceph starts moving data around the cluster to ensure the target number of replicas is maintained
  - You can disable this during maintenance using "noout"

Erasure Coding Pools



Proxmox and Ceph

- Proxmox has Ceph integrated
  - It can talk to Ceph storage
  - It can run as a Ceph storage cluster itself
- VMs and storage can run on the same hosts
  - a.k.a. "Hyperconverged"
  - This can make your cluster smaller and cheaper, but it can also make performance problems hard to diagnose
  - During healing, large amounts of RAM may be used by OSDs
    - allow 4GiB per OSD, *in addition* to VM memory
  - If you have large quantities of file or object data (other than VM images) it may be better to build a dedicated storage cluster for that

Ceph Lab